

Dependency Management in Distributed Settings

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1 Introduction

Applications in a computation and communication saturated pervasive-computing environment have to adapt their behaviors according to the context of the user and the physical space. These “context-aware” applications typically obtain high-level situational understanding by aggregating one or more outputs of distributed sensors.

To reduce the complexity of developing and deploying these adaptive applications, we designed and implemented a flexible software infrastructure, *Solar*, for large-scale context fusion [3]. *Solar* consists of a set of functionally equivalent nodes, named *Planets*, which peer together to form a service overlay. A sensor connects to a Planet to register a name with *Solar*’s *naming service* and publish a stream of *events*, while an application connects to a Planet to subscribe to one or more sensor outputs by querying *Solar*’s name space. In addition, applications may inject data-fusion *operators* into the *Solar* to reduce the computation and communication costs on the mobile devices.

In this paper we present our approach to address the dependency management issues in *Solar*. *Solar*’s *components* are sensors (their software processes), operators, and applications. We say a component *X* *depends* on another component *Y* if *X* needs events output from *Y*, and we say *X* is a *dependent* of *Y*. There are three problems: 1) to proactively monitor and recover lost components for their dependents; 2) to continuously evaluate application *Z*’s queries over the dynamic name space to select best sensors *Z* depends on; and 3) to garbage collect operators whose dependents has departed, to reclaim occupied resources.

Solar employs a peer-to-peer (P2P) routing substrate, named Pastry [4], in which each participating node (Planet) is assigned a key chosen randomly with uniform probability from a large identifier space. Each component in *Solar* has a unique key from the same space. In addition to normal IP transport with socket address as destination, *Solar* also provides a primitive to send a message to a key *K* based on Pastry’s router. The message eventually reaches the Planet whose key is numerically closest to *K* among all live Planets. We say this Planet is *responsible* for the key *K*.

2 Component registration

In *Solar*, a component must register by providing its key and a *configuration* as follows: 1) the action to take if *X* fails, such as to restart it or to email an administrator; 2) the command (or object class and initialization parameters) used to start *X*; 3) any restriction regarding the set of hosts where *X* be restarted; and 4) whether *Solar* can reclaim *X* when it has no dependents for certain time.

Some components may not be restarted on just any host. For instance, a sensor may have to run on a particular host, to access a piece of sensing hardware. On the other hand, most operators are self-sufficient, processing events as they arrive, so *Solar* may restart them on any available Planet when they are lost. *Solar* may also choose to migrate a running operator to balance load.

Solar requires each component to explicitly identify the set of components it depends on. A component may specify two types of dependencies: *key-based* or *name-based*. In other words, a component may specify the keys of the components it depends on, or a name query that will be resolved to discover components. Since our name service may return multiple components matching a query, the requesting component may use a selection function to select appropriate components. When data sources come and go, as is typical in a pervasive-computing environment, the results of the query change occasionally and the selection function is re-evaluated, permitting quick adaptation for the dependent [1].

For either type of dependency, the dependent supplies a policy determining how to handle the failure, restart, or migration of the other component, or (for name-based dependencies) a change in the results of the name query and selection function. For example, if *X* depends on *Y* and *Y* fails, the policy of *X* may be to wait until *Y* is restarted. If the $X \rightarrow Y$ dependency is name-based, another reasonable policy is to use the output of the selection function to choose a different component.

3 Monitoring and recovery

When a Planet *P* starts life, it finds another Planet P_M as its monitor by sending a request to a random key. The

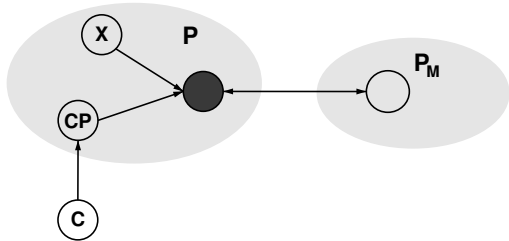


Figure 1. Component monitoring diagram.

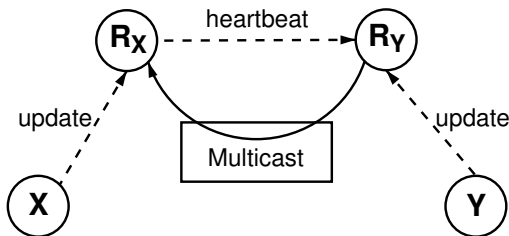


Figure 2. Dependency tracking diagram.

P registers the configurations of all its operators with P_M , and these two Planets engage in a heartbeat protocol between themselves. If P has not heard an update from P_M for a certain time, it assumes P_M has failed and finds another Planet as its monitor. If P_M has not heard an update from P for a certain time, it assumes P has failed and tries to restart all the operators originally running on P .

We now discuss how to monitor and recover an external client C (either a sensor process or an application). The idea is similar, client C and its serving Planet P run a dual monitoring protocol that detects each other’s liveness. As shown in Figure 1 the client C installs a proxy CP on its serving Planet. If C has failed, P tries to restart it if C ’s configuration contains instructions. Otherwise, it simply removes CP and de-registers C . On the other hand, the proxy CP is also being monitored by P_M . When P has failed, P_M does not try to recover CP but simply removes CP from the list of operators to be restored. If C is still alive while P has failed, C may go through a discovery protocol to find another Planet for service.

4 Tracking dependencies

In Solar, a component X may move from one Planet to another at runtime. We define a *root* object for X and denote it R_X , which tracks X ’s current location. The root always runs on the Planet responsible for X ’s key, so X ’s dependents can find X ’s location by simply sending a query to K_X . Root R_X receives periodic updates from X about its current location and dependency policies, as shown in Figure 2. Here we assume X depends on Y .

Upon receiving one of X ’s periodic update messages, R_X records X ’s current location and list of dependencies. If any dependency is name-based, R_X queries the naming service

and evaluates the selection function on the results. The output determines the component(s) X should use; X is notified about any changes in the selection and X updates R_X if it indeed made those changes. Thus R_X contains a list of keys of the components X currently depends on, whether explicitly specified or resolved from the name query.

Root R_Y receives notification whenever Y fails, restarts, or migrates from either Y ’s hosting Planet or its monitoring peer (P and P_M). Then R_Y publishes these events through Solar’s multicast service to channel T_Y [3]. Since R_X subscribes to the channels of the components X depends on, such as T_Y , these events trigger R_X to take actions specified in X ’s dependency policies, for instance, to re-evaluate a selection function to get other usable components if Y has failed. Note that, for scalability reasons, R_Y does not keep the keys of Y ’s dependents. Instead, it simply publishes events to a single channel subscribed by Y ’s dependents.

Given the list of keys X currently depends on, R_X sends a periodic *heartbeat* message to all the keys through Pastry at a low frequency. The root of each component receives the heartbeat and resets its timer; the timer fires when it has not heard any heartbeat from any dependents for a long time. Then that root, say R_Y for component Y , assumes there are no remaining dependents for Y . If Y ’s configuration permits, R_Y asks P_Y (the Planet currently hosting Y) to stop and de-register Y .

5 Summary

Our approach to dependency management in Solar requires each component to explicitly register a *recovery configuration* and all *dependencies*. Each Planet P has a peer monitoring Planet P_M that is responsible to initiate recovery, according to component configurations, if P_M detects the failure of P . On the other hand, the Planet responsible for the key of a component X tracks all the components X depends on and implements the associated policies when those components fail or when the result of X ’s name query and selection function change. We present the details of our protocols and experimental results in an extended report [2].

References

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